

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	252955	((382/100) or (244/3.16, 50,51,62,139,144,183, 190) or (250/287,390.08, 316.1,330,338.1,339.8, 339.11,339.14,341.8,342, 495.1)).CCLS. or ("340") or ("342") or ("343") or ("701")).CLAS.	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/04/20 15:18
L2	39607	1 and (detect\$4 or recogni\$5)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/20 15:25
L3	13252	2 and interfac\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/20 15:26
L4	2255	3 and (obstacle\$3 or barrier or snag or obstruct\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/04/20 15:24

L5	2106	4 and (display\$4 or output\$5)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:26
L6	1883	5 and (computer or processor\$3 or CPU or PC)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L7	1218	6 and software	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:26
L8	489	7 and (infrared or IR)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25

L9	127	8 and pixel\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:27
L10	110	9 and (aircraft or plane or airplane)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L11	67	10 and passive	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:27
L12	20	11 and platform	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:24

L13	3	12 and crew	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:23
L14	28	1 and (passive near4 obstacle)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:23
L15	18	14 and (detect\$4 or recogni\$5)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:24
L16	0	15 and (crew near4 interfac\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:24

L17	145	(crew near4 interfac\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:24
L18	31	17 and (obstac\$3 or barrier or snag or obstruct\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L19	6717	(mobile near4 platform)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L20	2344	19 and (aircraft or plane or airplane)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25

L21	613	20 and (detect\$4 or recogni\$5)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L22	185	21 and (obstacle\$3 or barrier or snag or obstruct\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L23	65	22 and (infrared or IR)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25
L24	61	23 and (computer or processor\$3 or CPU or PC)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:25

L25	61	24 and (display\$4 or output\$5 r monitor\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:26
L26	48	25 and software	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:26
L27	44	26 and interfac\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:27
L28	1	27 and (direct\$4 near4 flight\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:28

L29	11	27 and pixel\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:27
L30	8	29 and passive	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:28
L32	0	30 and (direct\$4 near4 flight\$4)	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:29
L33	1	30 and segment\$4	US-PGPU B; USPAT; USOCR; EPO; JPO; DERWEN T; IBM_TD B	OR	ON	2005/04/20 15:29



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## 1. An analog CMOS passive stereoscopic system for automated vehicle guidance

Arion, B.; Ni, Y.; Devos, F.;

Semiconductor Conference, 1996., International

Volume 1, 9-12 Oct. 1996 Page(s):135 - 138 vol.1

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| <input type="checkbox"/> | <p>2. <b>Toward stochastic modeling of obstacle detectability in passive stereo range imagery</b><br/>           Matthies, L.;<br/>           Computer Vision and Pattern Recognition, 1992. Proceedings CVPR '92., 1992 IEEE Computer Society Conf<br/>           15-18 June 1992 Page(s):765 - 768<br/> <a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a>(360 KB) IEEE CNF</p>              |
| <input type="checkbox"/> | <p>3. <b>Multi-sensor obstacle detection on railway tracks</b><br/>           Mockel, S.; Scherer, F.; Schuster, P.F.;<br/>           Intelligent Vehicles Symposium, 2003. Proceedings. IEEE<br/>           9-11 June 2003 Page(s):42 - 46<br/> <a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a>(493 KB) IEEE CNF</p>   |
| <input type="checkbox"/> | <p>4. <b>Visual detection of distant objects</b><br/>           Solder, U.; Graefe, V.;<br/>           Intelligent Robots and Systems '93, IROS '93. Proceedings of the 1993 IEEE/RSJ International Conference o<br/>           Volume 2, 26-30 July 1993 Page(s):1042 - 1049 vol.2<br/> <a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a>(948 KB) IEEE CNF</p>                               |
| <input type="checkbox"/> | <p>5. <b>Computer vision techniques for rotorcraft low-altitude flight</b><br/>           Sridhar, B.; Cheng, V.H.L.;<br/>           Control Systems Magazine, IEEE<br/>           Volume 8, Issue 3, June 1988 Page(s):59 - 61<br/> <a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a>(244 KB) IEEE JNL</p>   |
| <input type="checkbox"/> | <p>6. <b>A system for obstacle detection during rotorcraft low-altitude flight</b><br/>           Bhanu, B.; Roberts, B.; Duncan, D.; Das, S.;<br/>           Applications of Computer Vision, Proceedings, 1992., IEEE Workshop on<br/>           30 Nov.-2 Dec. 1992 Page(s):92 - 99<br/> <a href="#">AbstractPlus</a>   Full Text: <a href="#">PDF</a>(788 KB) IEEE CNF</p>                            |



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